

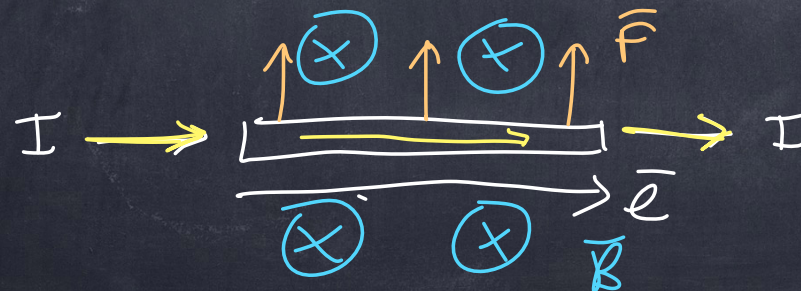
# PHY 117 HS2023

Week 10, Lecture 2

Nov. 22nd, 2023

Prof. Ben Kilminster

Yesterday:



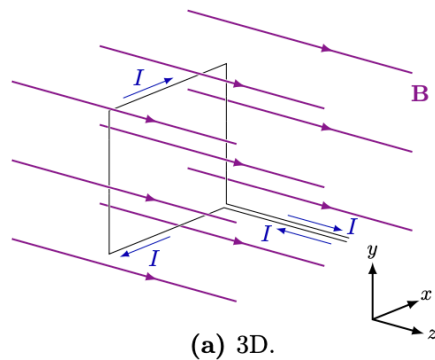
$$F = BIl$$

↑  
length of wire

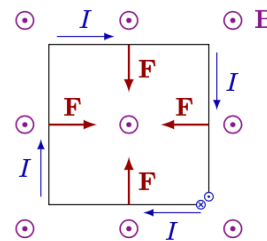
what about a loop of current?

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CHAPTER 7. MAGNETISM



(a) 3D.



(b) 2D in  $xy$  plane.

Figure 7.9: Rectangular current loop in an external, uniform magnetic field  $\mathbf{B} = B\hat{z}$ .

No net force,  
no net torque

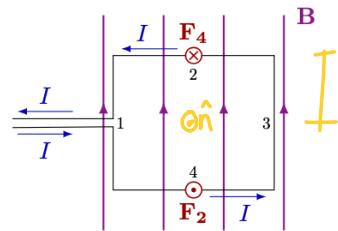


Figure 7.10: Rectangular current loop in an external magnetic field  $\mathbf{B}$ .

Here, there is torque

$$\vec{\tau} = \vec{r} \times \mathbf{F}$$

Segments 1 + 3 are parallel to  $\vec{B}$ ,  
so no force, no torque.

Segment 2:  $F_2 = BIl_2$ ,  $\tau_2 = \frac{l_1}{2} BIl_2 \hat{x}$

segment 4:  $F_4 = BIl_2$ ,  $\tau_4 = \frac{l_1}{2} BIl_2 \hat{x}$

The loop will twist from the torque  
(Notice  $\hat{n}$  of loop  $\perp \vec{B}$ )

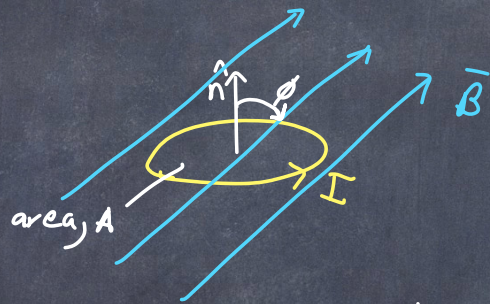
$$\text{Total torque} = \tau_z + \tau_\phi = \frac{l_1}{2} B I l_2 + \frac{l_1}{2} B I l_2 = I(l_1 l_2) B = I A B \hat{x}$$

$\hat{x} \leftarrow$        $\vec{\tau} \leftarrow$

$\uparrow$   
area

If loop  $\hat{n}$  is at an angle with respect to  $\vec{B}$ ,  
then in general

$$\vec{\tau} = I A \hat{n} \times \vec{B} = I A B \sin \phi$$



$\phi$ : is the angle from  $\hat{n}$  to  $\vec{B}$   
 $\hat{n}$ : normal direction  $\perp$  to the plane of the loop.

Torque is always in the direction that aligns  $\hat{n} \rightarrow \vec{B}$

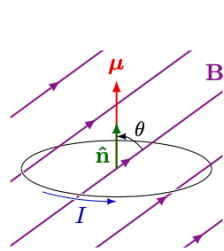
We can define the magnetic moment of the loop as  $\mu = I A$

and the  $\vec{\mu}$  vector

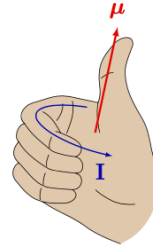
$$\vec{\mu} = (I A) \hat{n}$$

then

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

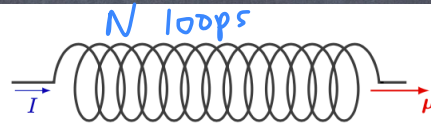


(a) Magnetic moment of a current loop in a uniform magnetic field.



(b) Right-hand rule for the magnetic moment of a current loop.

Figure 7.11: Magnetic moment.

Figure 7.12: Magnetic moment of a solenoid with  $N$  windings.

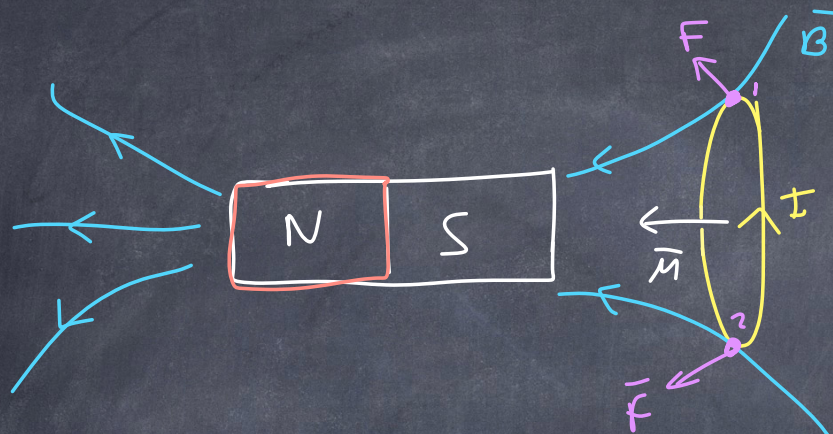
$$\bar{\mu} = N(IA) \hat{n}$$

The potential energy of a current loop in  $\vec{B}$ -field is

$$U = -\bar{\mu} \cdot \vec{B} + \text{constant}$$

we set the constant so that when  $\bar{\mu}$  is  $\parallel$  to  $\vec{B}$ , then  $U = 0$ .

What if the magnetic field is non-uniform?



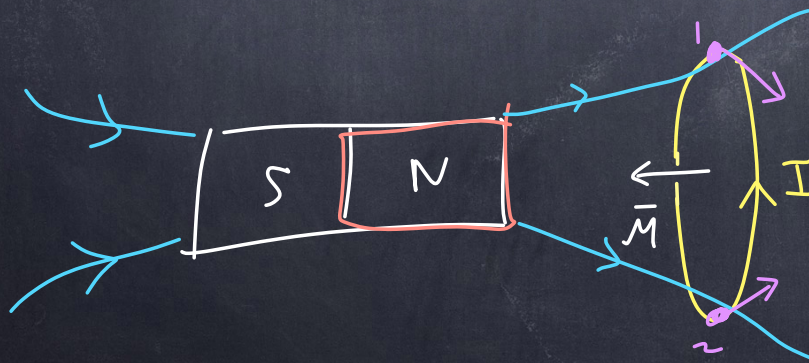
Consider 2 opposite points

$$1: \vec{F}_1 = q\vec{v} \times \vec{B} \quad \left. \begin{array}{l} \vec{v} = \otimes \\ \vec{B} = \leftarrow \end{array} \right\} \vec{F}: \nwarrow$$

$$2: \vec{F}_2: \left. \begin{array}{l} \vec{v} = \circ \\ \vec{B} = \leftarrow \end{array} \right\} \vec{F}: \swarrow$$

The net force is towards the magnet.

net force (vertical components cancel out)



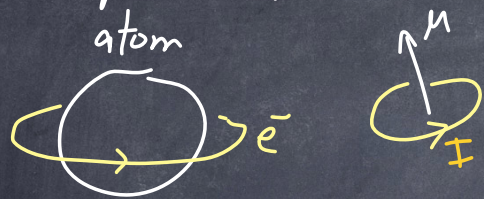
$$1: \vec{F}: \left. \begin{array}{l} \vec{v} = \otimes \\ \vec{B} = \rightarrow \end{array} \right\} \vec{F} = \searrow$$

$$2: \vec{F}: \left. \begin{array}{l} \vec{v} = \circ \\ \vec{B} = \rightarrow \end{array} \right\} \vec{F} = \swarrow$$

net force

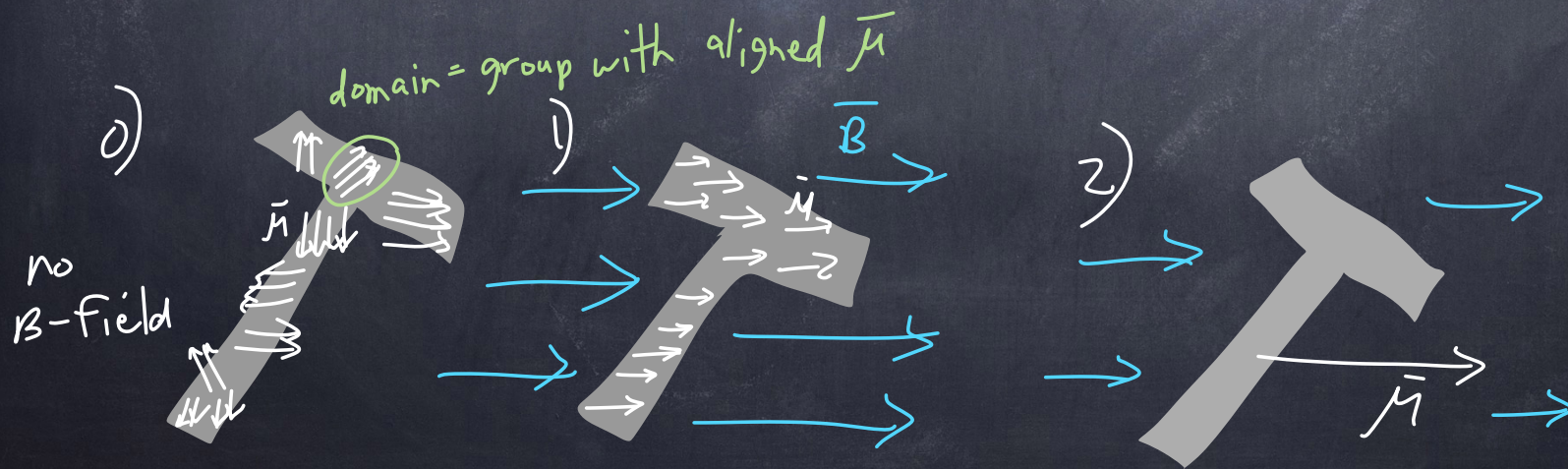
The net force is away from the magnet

Electrons and atoms can be thought of as spinning electric charges.

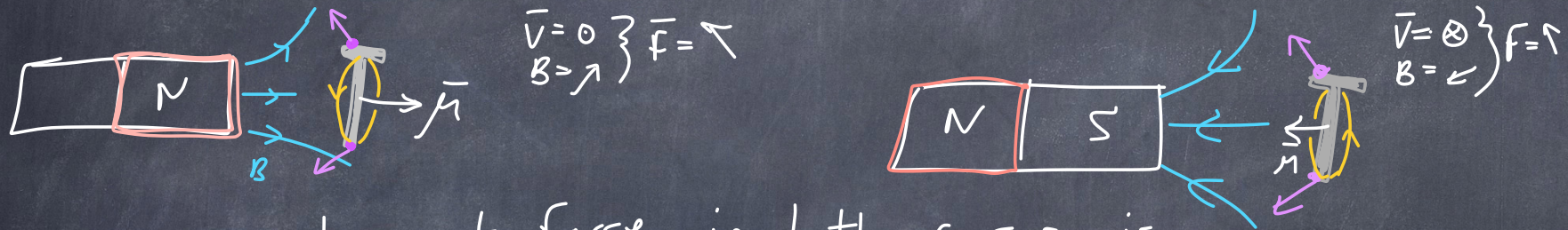


Each atom has a magnetic moment,  $\bar{\mu}$ .

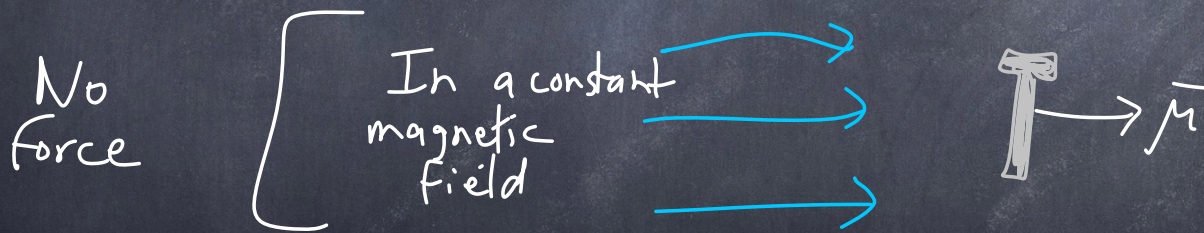
This helps us understand why an unmagnetized nail is attracted to a magnet, both the N + S side.  
This happens in a few steps:



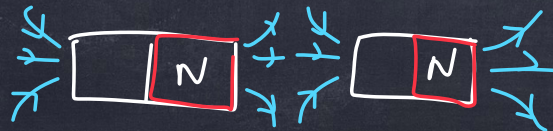
Why is nail attracted to N + S poles of magnet?  
 First, nail is magnetized in direction of field.  
 Second, divergent field causes a force of attraction.



The net force in both cases is toward the magnet.



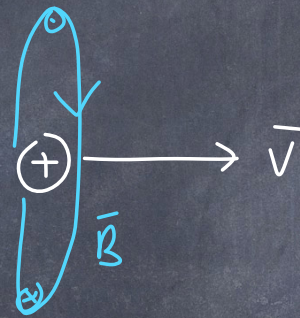
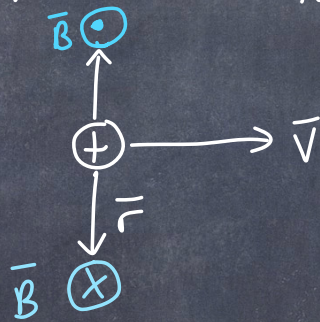
This is also why two magnets attract



So far, we know:  $\vec{F}_B = q\vec{v} \times \vec{B}$      $\vec{F} \perp \vec{v}, \vec{B}$   
 $\vec{F}_B = I\vec{l} \times \vec{B}$      $\vec{F} \perp \vec{l}, \vec{B}$

Now: A moving charge  $\oplus \rightarrow \vec{v}$   
 generates its own magnetic field.

The direction of  $\vec{B}$  is  $\vec{v} \times \vec{r}$



The magnetic field loops around the direction of motion.

The magnitude of  $B$  decreases like  $\frac{1}{r^2}$



$$\vec{B} = \frac{\mu_0}{4\pi} q \frac{\vec{v} \times \hat{r}}{r^2}$$

$\downarrow$  [T]       $\downarrow$   $\left[\frac{T \cdot m}{A}\right]$        $\uparrow$   $\frac{[C] \left[\frac{m}{s}\right]}{[m^2]}$

$\vec{B}$  caused by a moving charge.  
 $\mu_0$ : permeability of free space  
 $\uparrow$  vacuum

$$\mu_0 = 4\pi \times 10^{-7} \frac{T \cdot m}{A}$$

$$[A] = \left[\frac{C}{s}\right]$$

For a current, the form is

$$d\vec{B} = \frac{\mu_0}{4\pi} I \frac{d\vec{\ell} \times \hat{r}}{r^2}$$

Biot-Savart law:  
 Integrate to solve for  
 any shaped wire in  
 a B-field.

we won't do any exercises  
 with Biot-Savart law.

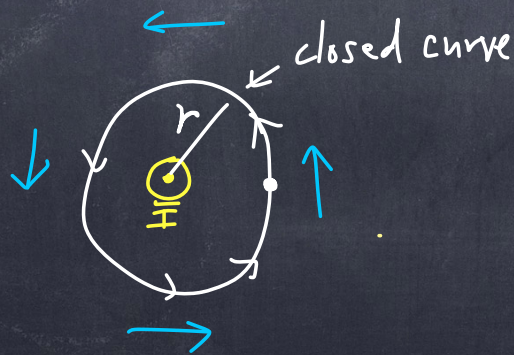
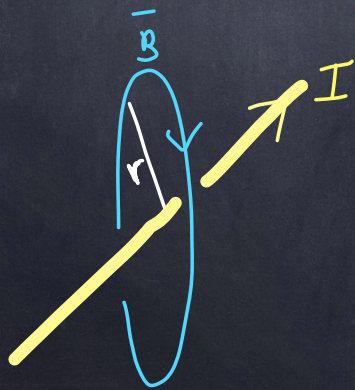
$$\vec{B} = \int \frac{\mu_0}{4\pi} I \frac{d\vec{\ell} \times \hat{r}}{r^2}$$

However, for simple configurations of current, there is an easier way. (like Gauss' Law)

Ampere's Law

$$\oint_{\text{closed curve}} \vec{B} \cdot d\vec{\ell} = \mu_0 I_c$$

$I_c$ : current passing through the closed curve.



We pick a curve where  $\vec{B} \parallel \vec{\ell}$

$$\oint_C \vec{B} \cdot d\vec{\ell} = \mu_0 I_c$$

$$B \oint_C d\ell = \mu_0 I$$

↓

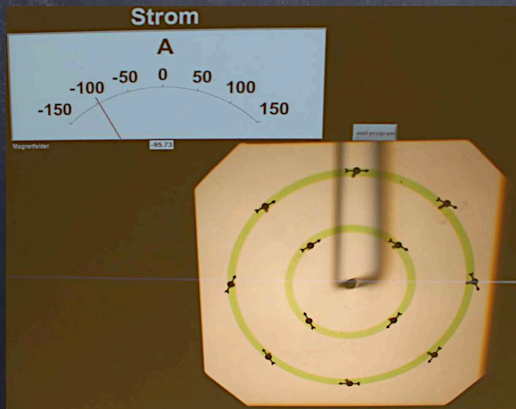
$$B (2\pi r) = \mu_0 I$$

$$B = \frac{\mu_0 I}{2\pi r}$$

$\oint_C d\ell = 2\pi r$ , the circumference of a circle

we see here:

$$B \propto \frac{1}{r} \quad B \propto I$$



using Ampere's law on a solenoid:

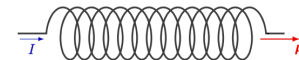
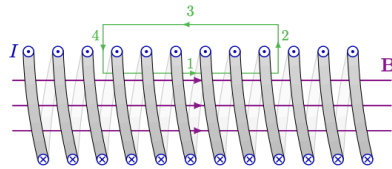


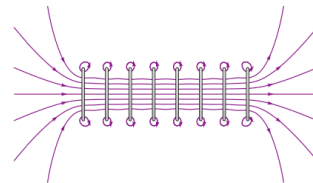
Figure 7.12: Magnetic moment of a solenoid with  $N$  windings.

8.2. AMPÈRE'S LAW

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(a) Using Ampère's law on a rectangular loop.



(b) Realistic field of a solenoid.

Figure 8.6: Magnetic field due to a solenoid.

sides 1 & 3 have length  $l$

$$n = \frac{N \text{ loops}}{\text{length}}$$

$$I_c = (nl)I$$

then  $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_c$

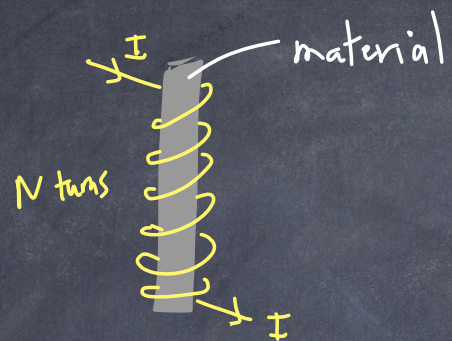
$$\underbrace{\int_1 \vec{B} \cdot d\vec{l}}_{\vec{B} \parallel d\vec{l}} + \underbrace{\int_2 \vec{B} \cdot d\vec{l}}_{\vec{B} \perp d\vec{l}} + \underbrace{\int_3 \vec{B} \cdot d\vec{l}}_{\vec{B} \approx 0} + \underbrace{\int_4 \vec{B} \cdot d\vec{l}}_{\vec{B} \perp d\vec{l}} = \mu_0 n l I$$

$$B = \mu_0 n I$$

$$B = \mu_0 n I = \mu_0 \frac{N}{l} I$$

magnetic field in a hollow Solenoid.

If there is a material inside,



$$B = \mu n I \quad \text{where } \mu = \mu_0 \mu_r$$

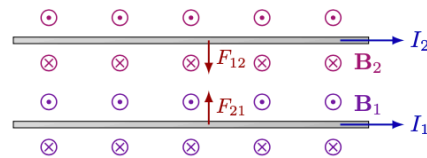
Here,  $\mu_r$  is the relative permeability

<u>material</u>	<u><math>\mu_r \left( \frac{\mu}{\mu_0} \right)</math></u>
air	1.000 000 37
water	0.999 99 2
Copper	0.999 99 4
pure iron (99.95%)	2 00 000
iron 99.8%	5 000

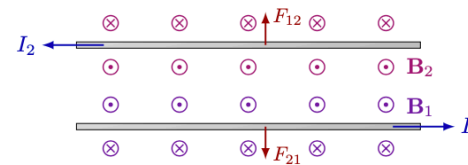
A current  $I_1$  produce a magnetic field  $B_1 = \frac{\mu_0 I_1}{2\pi r}$   
 Another current  $I_2$  will feel a force from  $B_1$ :  $F = B_1 I_2 l$

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CHAPTER 8. LAWS OF MAGNETISM



(a) Parallel current.



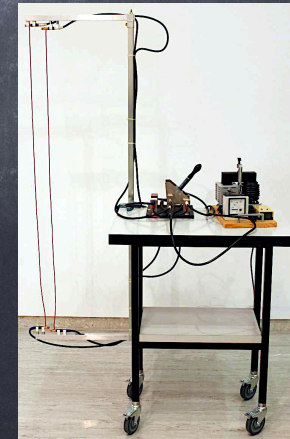
(b) Anti-parallel current.

Figure 8.7: Magnetic force between current-carrying wires.

$$F_{12} = \frac{\mu_0 I_1 I_2 l}{2\pi r}$$

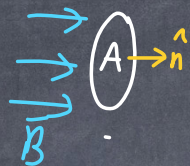
also  $\vec{F}_{12} = -\vec{F}_{21}$

attractive or repulsive!



Magnetic flux:

For a loop  $\perp$  to  $\vec{B}$ -field



we can quantify the  $\vec{B}$ -field by

$$\Phi_m = BA$$

A: area

where  $\Phi_m$  is known as the magnetic flux

If  $\hat{n}$  is not  $\parallel$  to  $\vec{B}$ , then

$$\Phi_m = \vec{B} \cdot \hat{n} A = BA \cos \theta$$



units are Weber:

$$1 [\text{Wb}] = 1 [\text{T} \cdot \text{m}^2]$$

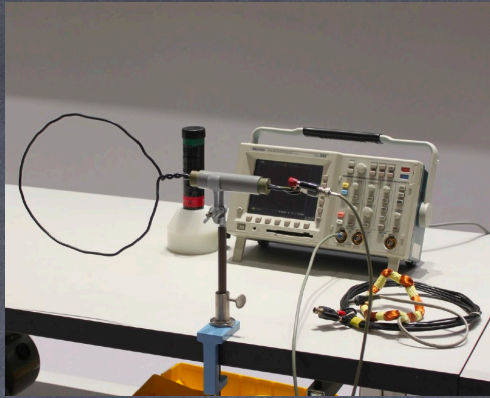
If magnetic flux changes, an electric field will be produced. The electric field produces an  $\mathcal{E}$ mf

$$\mathcal{E} = \oint_C \vec{E} \cdot d\vec{\ell} = - \frac{d\Phi_m}{dt}$$

↑  
Voltage  
supplied

Known as  
Faraday's Law.

$$\text{Notice } [V] = \left[ \frac{\text{Wb}}{\text{s}} \right]$$



$\Phi_m = \vec{B} \cdot \hat{n} A$   
can be changed by  
changing  $B$  or  $A$  or  $\hat{n}$ !

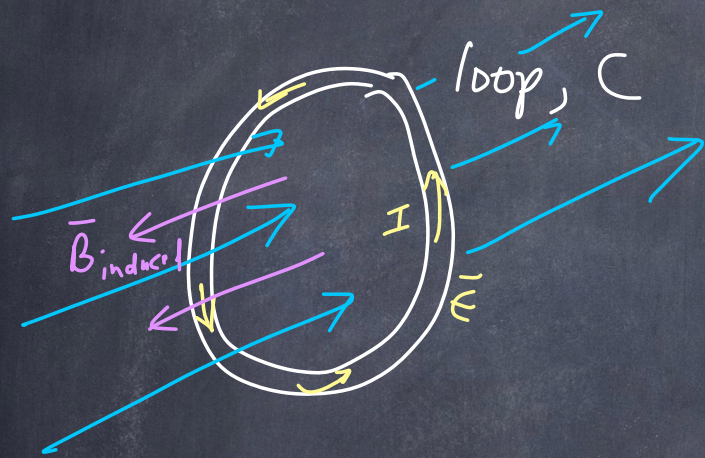
If magnetic flux changes, an electric field will be produced. The electric field produces an  $\mathcal{E}$ mf. This electric field means that a current is produced. But a current produces a magnetic field! what?

Lenz's Law: "The induced  $\mathcal{E}$ mf and induced current are in such a direction so as to oppose the change that produces them."



This means:

1) A moving magnet induces magnets in the opposite direction.

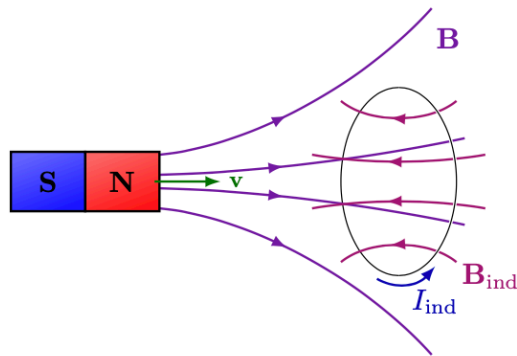


$\vec{B}$  is + increasing

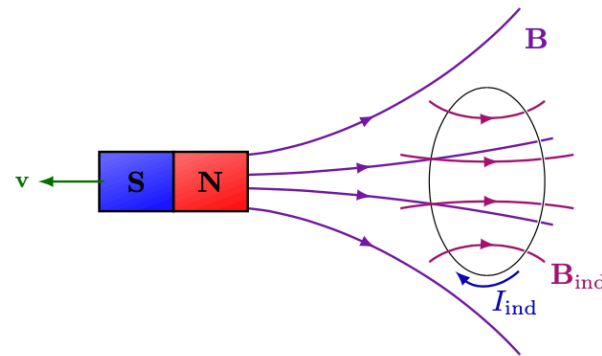
If we increase  $\vec{B}$ ,  
 $I$  is produced.

(But in opposite direction)

$\vec{B}_{\text{induced}}$  opposes changes in  $\vec{B}$



(a) Field moving toward the loop.



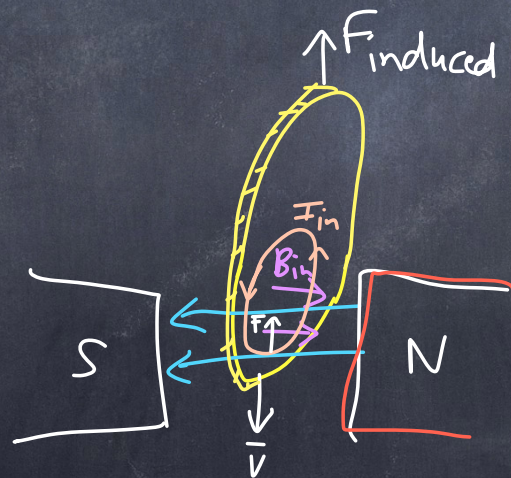
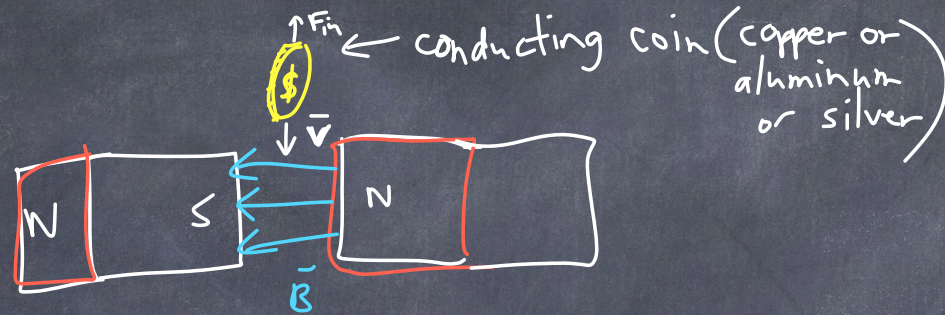
(b) Field moving away from the loop.

**Figure 8.8:** The magnetic field  $\mathbf{B}$  of a moving bar magnet will induce a current  $I_{\text{ind}}$  in a conducting loop and therefore a magnetic field  $\mathbf{B}_{\text{ind}}$ .

If  $\vec{B}$  increases,  $\vec{B}_{\text{ind}}$  is opposite  $\vec{B}$

If  $B$  decreases,  $\vec{B}_{\text{ind}}$  is in the same direction as  $\vec{B}$





we call induced currents  
"Eddy currents"



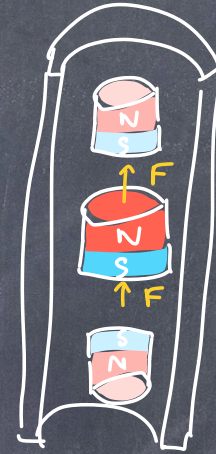
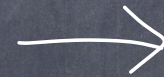
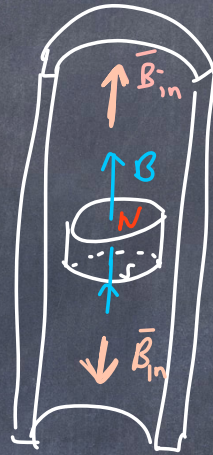
cutout prevents  
Eddy currents



As magnet falls:

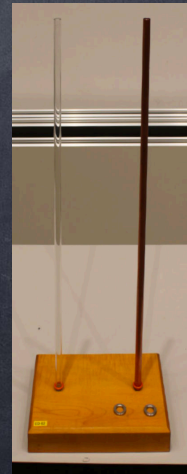
$\vec{B}$  decreases above magnet

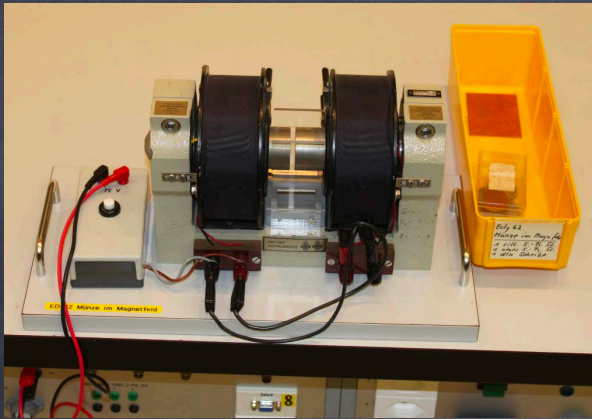
$\vec{B}_{in}$  is same direction as  $\vec{B}$



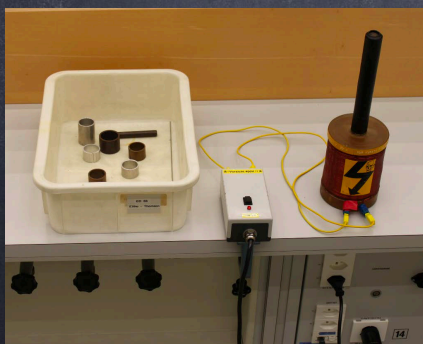
$\vec{B}$  increases below the magnet

$\vec{B}_{induced}$  opposite of  $\vec{B}$



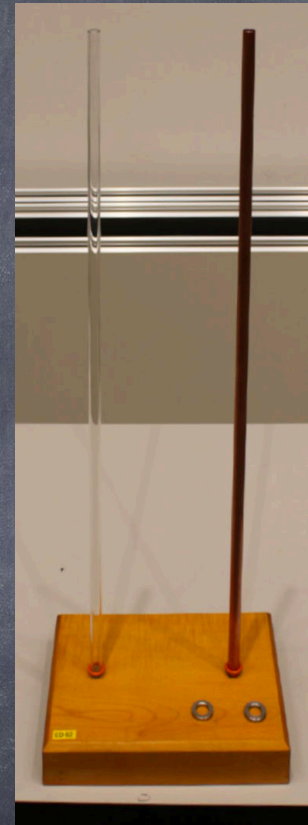


Dropping a conductor  
in a magnet



turning a conductor into  
an opposing magnet

cutout  
prevents  
Eddy currents

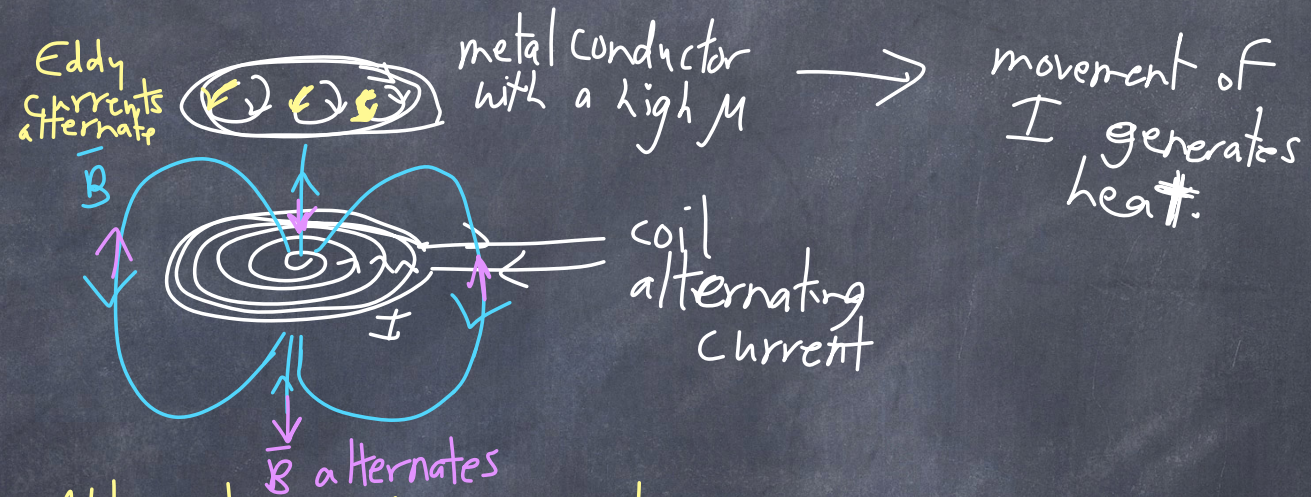


dropping magnet in  
a conductor

## Summary of magnetic field concepts:

- 1) A moving electric charge may feel a force from a magnetic field.
- 2) A moving electric charge generates its own magnetic field. (A changing electric field produces a magnetic field.)
- 3) A changing magnetic field generates electric currents that produce an opposing magnetic field.

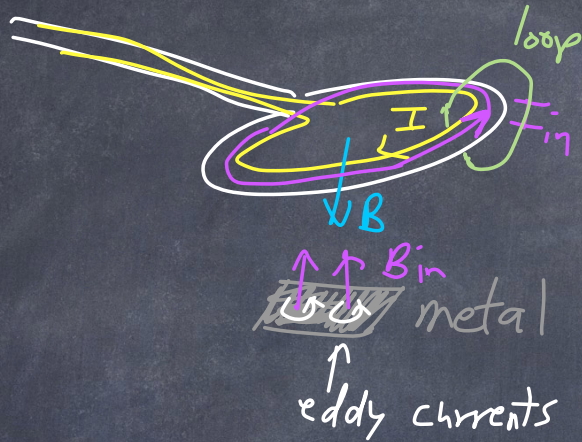
Induction stove uses Eddy currents?



Alternating eddy currents generate heat in a conductor (Joule heating)

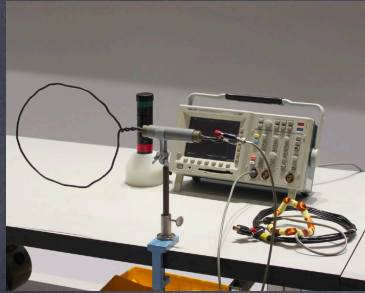


Metal detector uses Eddy currents



$I_{in}$  is generated  
in opposite direction,  
tends to decrease  
current in metal  
detector.

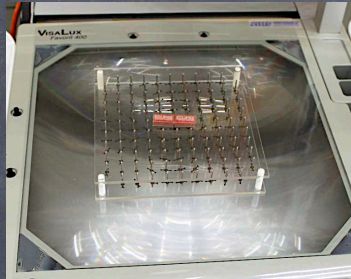
Metal detector searches  
for currents in  
opposite directions.



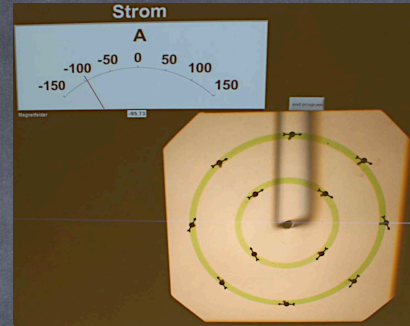
ED48



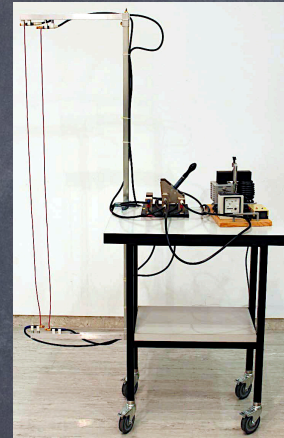
ED63



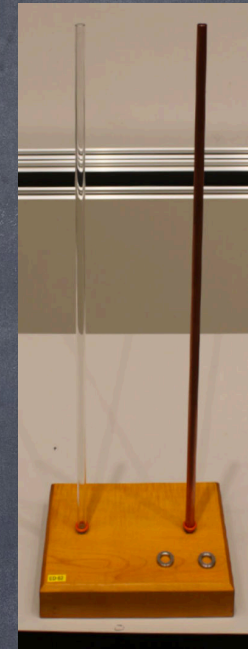
ED6



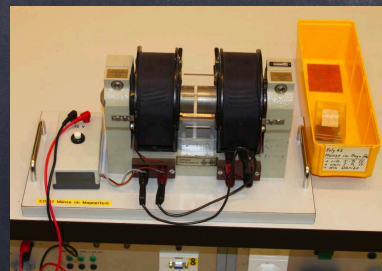
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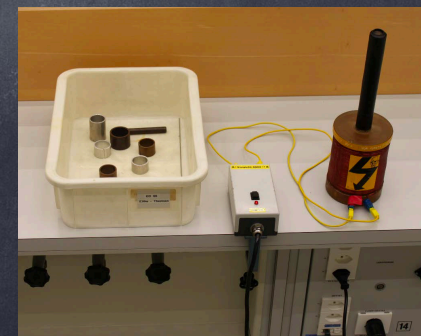
ED14



ED62



ED61



ED66